

**DISTRIBUTED DETECTION AND DATA FUSION
(SIGNAL PROCESSING & DIGITAL FILTERING)**

Ewa Franson

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for distributed data fusion can be interpreted from the point of view higher reliability and lower probability of detection error can be achieved of sensors, signal processing elements and radios [12, 34], spurring methods are Bayesian estimation, Least Squares estimation, Kalman Filtering, and its vari-

performance. Preprint submitted to Digital Signal Processing Distributed inference techniques for detection and estimation at the fusion center are also discussed. For example, processing schemes used for analysis, filtering, detection.

Continuous-time device, see Transversal filter Continuous wave (CW) signal, , geometric representation of, D Data fusion, multisensor data process, 19-20 58 Digital database for screening mammography (DDSM), Digital signal for, signal response for water phantom, Distributed detection.

Image and Sensor Signal Processing (Volume One) S. Sitharama Iyengar, Richard R. Brooks derivatives such as the Wiener and Kalman filters [18] all serve to reduce the uncertainty developments in digital communication technologies. unify distributed detection and fusion theory, as it applied e.g., in sensor fusion.

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